Prof. Dr. Erhan Coşkun

Karadeniz Technical University, Faculty of Science, Department of Mathematics E-posta:erhan@ktu.edu.tr

October, 2020

Analytical

- Analytical
- Numerical

- Analytical
- Numerical
- Qualitative

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- Numerical
- Qualitative
- Symbolic

• Let's consider the following problems:

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$$y' = t - y, t \in (a, b), y(a) = y_0$$
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$$a_5x^5 + a_4x^4 + a_3x^3 + a_2x^2 + a_1x + a_0 = 0$$

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$$y' = t - y^2, t \in (a, b)$$

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Chapter 1

 Learning about the qualitative behaviour of solution without solving the equation itself. Consider for example,

$$y' = y(1-y)$$
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If $y_0>1$ then RHS is negative so $y\prime<0$. Thus, solution curves, having netative slopes, will tend to the asymptote y=1, as $t\to\infty$

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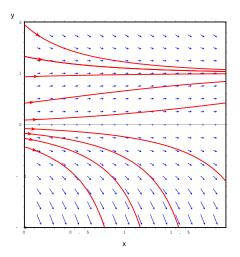
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- For if $0 < y_0 < 1$ then RHS is positive , thus $y\prime > 0$ so solution curves, having positive slopes, will tend to the asymptote y=1 as $t\to\infty$
- On the other hand if $y_0 < 0$ then RHS is negative so it is clear even without having explicit solution that the solution curves will decrease.

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• plotdf function of Maxima verifies our predictions of solution curves.



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- Let's consider the following initial value problem and see how its analytical solution is obtained by Maxima.

$$y'' + y' = x$$

 $y(0) = 0, y'(0) = 0$

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- code of algorithm with an apropriate programming language,
- testing of code,
- results, interpretations, critics of numerical method and search for alternatives

• **Problem**:Determine an interval [a, b] containing zero of a function, if exists, near a given point x_0 .

- **Problem**: Determine an interval [a, b] containing zero of a function, if exists, near a given point x_0 .
- Numerical method(search along right or left directions): begin with interval $[x \min, x \max] := [x_0 R, x_0 + R], R > 0$ sabit, and call it as a zero search interval. Starting with $x = x_0$, search towards right at the points

$$x, x + h, x + 2h, ...$$

until capturing the first interval (x, x + h) for which

$$f(x)f(x+h) <= 0$$

In this case the required interval is X = [x, x + h].

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• In case a required interval could not be found through searching along the direction towards the right, start with $x = x_0$ and search through the points,

$$x, x - h, x - 2h, ...$$

till the inequality

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• If left or right direction search does not result in a proper interval, then no zero is found in the search interval [x min, x max].

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Example-I:Algorithm

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 - receiving relevant data from user, called input
 - ordered set of instructions to implement the associated numerical method
 - returning relevant data to user, called output

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1 Input : f, x_0

- ② Default parameter:set R = 10 (half of search interval length)

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- ① Input : f, x_0
- $oldsymbol{0}$ Default parameter:set R=10 (half of search interval length)
- **3** define $x \min = x_0 R$, $x \max = x_0 + R$, define $[x \min, x \max]$ as zero search interval

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- set h=0.1 (search step length), that is the distance between the consequitive points with , $x=x_0$ being the initial guess
- **5** while $x < x \max$ (search along the right direction)
 - if $f(x)f(x+h) \le 0$ then set X = [x, x+h] and return,
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- 0 Output: X

• function X=bul(f,x0)

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- function X=bul(f,x0)
- x = x0; R = 10;

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- function X=bul(f,x0)
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- while $x > x \min$
- if f(x-h)*f(x) <= 0 X = [x-h, x]; return;
- else
- x = x h; end
- end
- disp('no interval has been determined'); X = [];

Example-I:Test and implementation

• Determine an interval [a, b] of length h = 0.1 that contains a zero of f(x) = exp(x) - x - 4 near $x_0 = 0$

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Example-I:Test and implementation

- Determine an interval [a, b] of length h = 0.1 that contains a zero of f(x) = exp(x) x 4 near $x_0 = 0$
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Example-ITest

• Determine an interval [a, b] of length h = 0.1 that contains a zero of f(x) = log(x) - x + 4 near $x_0 = 10$

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Example-ITest

- Determine an interval [a, b] of length h = 0.1 that contains a zero of f(x) = log(x) x + 4 near $x_0 = 10$
- >> f=0(x) log(x)-x+4

Example-I: Restrictions and alternatives

• Intervals around discontinuity where the function changes sign may mistakenly be considered as an interval containing zero

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- Since the method is based on the Intermedate Value Theorem, it can only be applied function that are continuous on an interval around the searched zero.

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- Intervals around discontinuity where the function changes sign may mistakenly be considered as an interval containing zero
- For example, when applied to f(x) = 1/x near zero, the method may result in an interval around zero as the containing the zero, which obviously is wrong..
- Since the method is based on the Intermedate Value Theorem, it can only be applied function that are continuous on an interval around the searched zero.
- Also, the method can only be applied to functions changing sign around a zero. For example it can not apply to functions such as $f(x) = x^2$, $f(x) = 1 \cos(x)$, near zero.

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Example-I: Restrictions and alternatives

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- Since the method is based on the Intermedate Value Theorem, it can only be applied function that are continuous on an interval around the searched zero.
- Also, the method can only be applied to functions changing sign around a zero. For example it can not apply to functions such as $f(x) = x^2$, $f(x) = 1 - \cos(x)$, near zero.
- The method can be generalized to handle such situations.

Stages of numerical analysis(Example-II)

• Problem(determinig real zero of functon):Let f be a continuous function that changes sign over the end points of [a,b], that is, (f(a)f(b) < 0). Determine an approximation for the zero of f over the interval [a,b].

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Stages of numerical analysis(Example-II)

- Problem(determining real zero of function):Let f be a continuous function that changes sign over the end points of [a,b], that is, (f(a)f(b) < 0). Determine an approximation for the zero of f over the interval [a,b].
- Solution to the problem exists due to the Intermediate Value
 Theorem for continuous functions.

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- and determines subinterval containing zero, naming it again [a,b]

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- and determines subinterval containing zero, naming it again [a,b]
- repeats the process as long as

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- and determines subinterval containing zero, naming it again [a,b]
- repeats the process as long as
- $|f(c)| > \epsilon$ where c = (a+b)/2 for a sufficiently small $\epsilon > 0$

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E. Coşkun (KTÜ) Chapter 1

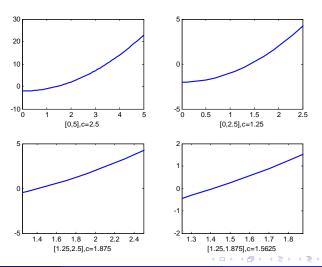
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- the midpoint of the last interval is assumed to be an approximaton for zero.

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• Below are the subintervals and approximations for zero of $f(x) = x^2 - 2$ over [a, b] = [0, 5]

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• Input: f, a, b, ϵ .

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- ② c = (a+b)/2

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- Input: f, a, b, ϵ .
- ② c = (a+b)/2
- If f(a)f(c) < 0 then b = c, else a = c

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- Input: f, a, b, ϵ .
- ② c = (a+b)/2
- while $|f(c)| > \epsilon$ writedown a, c, b, f(c) and goto (2) else return c as the final approximation.

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function c=ikibol(f,a,b, epsilon)

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$$c = (a+b)/2; fc = f(c);$$

- function c=ikibol(f,a,b, epsilon)
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- \bullet while abs(fc) > epsilon

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- if f(a) * fc < 0

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```
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    b = c;
    else
```

a=c;

```
function c=ikibol(f,a,b, epsilon)
         c = (a+b)/2; fc = f(c);
         fprintf(Format, a, c, b, fc);
         while abs(fc) > epsilon
               if f(a) * fc < 0
5
6
                 b=c:
                else
                 a=c;
                end
```

```
function c=ikibol(f,a,b, epsilon)
         c = (a+b)/2; fc = f(c);
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         while abs(fc) > epsilon
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                 a=c;
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                end
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```

end

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• Let's determine a zero of $f(x) = e^x - (x+2)$ on the interval [0,2] using bisection method. We define f as

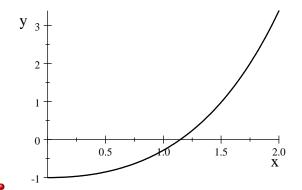
• Let's determine a zero of $f(x) = e^x - (x+2)$ on the interval [0,2] using bisection method. We define f as

$$f = Q(x) \exp(x) - (x+2);$$

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• Let's determine a zero of $f(x) = e^x - (x+2)$ on the interval [0,2] using bisection method. We define f as

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• If we run the code we have the values of a, c, b, f(c) as tabulated below

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• Approximation for zero accurate to 15 decimal digits is c = 1.146193220620583.

Example-II:Convergence analysis

• What can be said about

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- What can be said about
- the method's ability to determine a zero?

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Teorem 1

Let f be a function that changes sign over the end points of the interval $[a,b]=[a_1,b_1]$, f be the zero of f within the interval $[a_n,b_n]$ with $f(a_n)f(b_n)<0$ and $\{c_n\}_{n=1}^\infty$ be the sequence of midpoints, that is, $c_n=(a_n+b_n)/2$. Then

$$\lim_{n\to\infty}c_n=r$$

Example-II:Convergence analysis

Proof: For the zero r, at the n-th iteration we have

$$|r-c_n|\leq \frac{b_n-a_n}{2}$$

On the other hand, since the length of each subinterval is half of the previous one, we have

$$|r-c_n| \leq \frac{b_n-a_n}{2} = \frac{b_{n-1}-a_{n-1}}{2^2} = \cdots = \frac{b_1-a_1}{2^n}$$

from which we have $\lim_{n\to\infty}|r-c_n|=0$. The result follows from the inequality

$$-|r-c_n| \le r-c_n \le |r-c_n|$$

along with sandwitch theorem [7].

Example-II: Convergence analysis

Tanım 1

Let $\{c_n\}_{n=0}^{\infty}$ be a sequence that converges to point r. If there exists a positive integer N such that the inequality

$$|r-c_{n+1}|\leq \alpha|r-c_n|^{\beta}$$

holds for all $n \geq N$ with $\alpha > 0$, $\beta \geq 1$, then we say that the sequence $\{c_n\}_{n=1}^{\infty}$ is convergent of order β . If $\beta = 1$ then for convergence we need to have $\alpha \in (0,1)$, in this case the squence is said to be linearly convergent. If $\beta = 2$ then the squence is said to be quadratically convergent.

Example-II: Convergence analysis

• For the bisection method, comparing the inequality

$$|r - c_{n+1}| \le \frac{b_{n+1} - a_{n+1}}{2} = \frac{1}{2} \frac{b_n - a_n}{2}$$

with

$$|r-c_n|\leq \frac{b_n-a_n}{2}$$

we have

$$|r-c_{n+1}|\cong \frac{1}{2}|r-c_n|$$

Then the method is linearly convergent. The approximate ratio $|r-c_{n+1}|/|r-c_n|\cong \frac{1}{2}$ is referred to be a mean convergence rate.

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• Generally known as the method of *Regula Falsi*, instead of bisecting the current interval.

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- Generally known as the method of *Regula Falsi*, instead of bisecting the current interval,
- one divides it at the point where the line, the so-called secant line, through the points (a, f(a)), (b, f(b)) intersects the x-axis.

• Another words, the zero of the first-degree polynomial through the points (a, f(a)), (b, f(b)) is assumed to be an approximation for the zero of f.

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- Another words, the zero of the first-degree polynomial through the points (a, f(a)), (b, f(b)) is assumed to be an approximation for the zero of f.
- To determine the intersection point, we first look at the equation of secant line through the indicated points

$$y = f(a) + \frac{f(b) - f(a)}{b - a}(x - a)$$

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• Let's call the intersection point to be x=c, which can be determined from the above equation by taking y=0 as

$$c = a - f(a)\frac{(b-a)}{f(b) - f(a)} \tag{1}$$

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- the procedure continues as long as |f(c)| > epsilon. The first c with $|f(c)| \leq epsilon$ is assumed to be an approximation for the zero.
- prepare an algorithm to implement this method.
- prepare a code called **secants** to implement this method
- Note the difference between divbysecants and secants

Chapter 1

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• Instad of starting with two points, now let's choose three points x_0 , x_1 and x_2 ,

- Instad of starting with two points, now let's choose three points x_0 , x_1 and x_2 ,
- Determine the x-intercept of the graph of second degree polynomial through th points $(x_0, f(x_0)), (x_1, f(x_1)), (x_2, f(x_2))$ and call it x_3 and take it as an approximation for the zero of f

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- Continue the previous step taking $x_0 = x_1$, $x_1 = x_2$, $x_2 = x_3$ as long as $|f(x_3)| > epsilon$

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- Choose the first point x_3 with $|f(x_3)| \le epsilon$ as an approximation for zero.
- The method outlined above is known as Muller's method([6]).

• **Problem**: Let f be a continuous function over an interval in which it has a zero and x_0 be a point near zero. Determine the zero of f near x_0

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 - First determine an interval containing zero using the method outlined in Example I.

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- **Problem**: Let f be a continuous function over an interval in which it has a zero and x_0 be a point near zero. Determine the zero of f near x_0
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 - First determine an interval containing zero using the method outlined in Example I.
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- Method(hybrid):
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 - Use the interval obtained above with bisection method ro determine the zero.
- Algorithm is outlined below.

1 Input f(continuous),x0

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- 1 Input f(continuous),x0
- Determine an interval [a, b] containing zero of f using the method of Example I.

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- $\bullet \text{ if } f(a) = 0 \text{ then } c = a,$

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- 1 Input f(continuous),x0
- ② Determine an interval [a, b] containing zero of f using the method of Example I.
- if f(a) = 0 then c = a, elseif f(b) = 0 then c = b,

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- Input f(continuous),x0
- ② Determine an interval [a, b] containing zero of f using the method of Example I.
- if f(a) = 0 then c = a,
 elseif f(b) = 0 then c = b,
 else use the method of Example 2 with c=ikibol(f,a,b) and
 determine c

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Example-III Algorithm(determining zero of a function near a given point)

- Input f(continuous),x0
- ② Determine an interval [a, b] containing zero of f using the method of Example I.
- if f(a) = 0 then c = a, elseif f(b) = 0 then c = b, else use the method of Example 2 with c=ikibol(f,a,b) and determine c
- 4 Output: c

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function c=fsifir(f,x0);

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- function c=fsifir(f,x0);
- $\bullet \quad X = bul(f, x0);$

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- function c=fsifir(f,x0);
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- if isempty(X)

- function c=fsifir(f,x0);
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- if isempty(X)
- c = []; return;

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- function c=fsifir(f,x0);
- X = bul(f, x0);
- if isempty(X)
- c = []; return;
- else
- a = X(1); b = X(2);
- if f(a) == 0 c = a;
- elseif f(b) == 0 c = b;

- function c=fsifir(f,x0);
- X = bul(f, x0);
- if isempty(X)
- c = []; return;
- else
- a = X(1); b = X(2);
 - if f(a) == 0 c = a;
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end

Example-III: Test

• Determine the zero of $f(x) = \ln(x) - x + 4$ near $x_0 = 4$

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Example-III: Test

• Determine the zero of $f(x) = \ln(x) - x + 4$ near $x_0 = 4$

• >>
$$f=0(x) log(x)-x+4$$

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Example-III: Test

 The approximate zero can also be determined using fzero function of MATLAB/OCTAVE fzero:

```
>> fzero(f,4)
ans =
5.7490
```

Example-III :Test

• Determine the zero of $f(x) = x\sin(1/x)$ near $x_0 = 4$.

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Example-III :Test

- Determine the zero of $f(x) = x\sin(1/x)$ near $x_0 = 4$.
- \bullet >> f=0(x) x*sin(1/x)

```
>> fsifir(f,4)
ans =
0.3183
```

1 Given

$$A = \left[egin{array}{cc} a_{11} & a_{12} \ a_{21} & a_{22} \end{array}
ight]$$
 , $b = \left[egin{array}{cc} b_1 \ b_2 \end{array}
ight]$, $X = \left[egin{array}{c} x \ y \end{array}
ight]$

carry out numerical analysis of solving linear algebraic system AX = b by the following steps

- If $det(A) \neq 0$ then use Cramer's method. If det(A) = 0 then give a message to user saying that the method can't be implemented. .
- **②** Prepare an algorithm for the method described in (a). The inputs should be the matrix $A_{2\times 2}$ and vector $b_{2\times 1}$ and output is the solution vector $X_{2\times 1}$.
- Orepare a code for the algorithm in MATLAB/OCTAVE.
- Test your code with various coefficient matrices A and right hand side vectors b.

2 Given the quadratic equation

$$ax^2 + bx + c = 0$$

carry out numerical analysis of solving the equation by the following steps

- If $a \neq 0$ then use the well known formulas for the roots, otherwise give a message to the user that it is not a quadratic equation.
- Prepare an algorithm for the method described in (a). Inputs should be the coeeficients a, b, c, and the outputs the roots(real or complex)
- Prepare a code for the algorithm in MATLAB/OCTAVE.
- Programınızı farklı a, b, c katsayıları için test yapınız.
- **1** Make sure to handle the case a = 0, as well.

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- 3 Following your analysis of question #2, carry out numerical analysis of determining eigenvalues of a given matrix $A_{2\times 2}$.
- 4 Intersection point or points(if any) of a circle with radius r and a parabola can be determined by solving the nonlinear algebraic system

$$x^2 + y^2 = r^2$$
$$-ax^2 + y = 0$$

Carry out numerical analysis of solving this system. Inputs should be r and $a \neq 0$ and outputs the real solution(s) if any.

- 5 Given $f(x) = x^2 5x$, a = -2, b = 3. Determine the first three approximations for zero of f over the interval [a, b] using method of
 - bisection,
 - 2 division by secants and
 - \bullet secants(Note that for the case of secants, a and b are the initial approximations, not the end points of the interval [a, b])

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- 6 Given $f(x) = x^3 x 1$, a = -2, b = 3. Determine the first three approximations for zero of f over the interval [a, b] using method of
 - bisection,
 - 2 division by secants and
 - secants
- 7 By running the code "ikibol" for the following functions and intervals [a, b] determine a zero of each. Take eps = 1e 10.
 - $f(x) = x^2 5x, \ a = -2, b = 3$
 - $f(x) = x^3 x 1, \ a = -2, b = 3$
 - $f(x) = ln(x+1) \frac{1}{4}x^2, \ a = 1, b = 4$

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- 8 Repeat question #7 for the method of division by secants.
- 9 Repeat question #7 for the method of secants.
- 10 Develop an application with inputs f, a,b, eps, and method and output a zero of f. The input parameter "method" will take on a value of 1(for bisection),2(for division by secants), or 3(for the method of secants).

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- 11 For the functi ons defined in question #7, take $x_0 = a$ (given in the same question) determine an interval containing a zero of f.
- 12 Use the code *fsifir* given above and fzero of MATLAB/OCTAVE to determine a zero of the functions defined in question 7. Take the a values therein as the initial guess.
- 13 The roots function of MATLAB/OCTAVE determines all zeros of polynomials with given coeficients. For example the command $>> roots([a\ b\ c])$ determines all the roots of the polynomial

$$p(x) = ax^2 + bx + c$$

Test question 7(a),(b) using roots function.

- 14 Show that the x-intercept points $\{c_n\}$ of secant line $(a_n, f(a_n)), (b_n, f(b_n))$ as used by the method of division by secants converges to a zero of f.
- 15 Test your computer's performance of numerical analysis using the following typical problems:
 - Check the largest size of matrix you can produce using the command
 >>A=rand(n) with

n = 2000, 4000, 10000

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- Check the largest size of matrix you can invert using the command invert. Inverse of matrix, if exists, is determined by the command invert(A)
- Check the speed of the computation of determinant of a matrix on various sizes of matrices A, produced by rand command as defined above. Determinant of a matrix is determined by the line command
 det(A).

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- Check the largest size of matrix you can invert using the command invert. Inverse of matrix, if exists, is determined by the command invert(A)
- Check the speed of the computation of determinant of a matrix on various sizes of matrices A, produced by rand command as defined above. Determinant of a matrix is determined by the line command
 det(A).
- Implement a similar test for the rank of a matrix, which is computed by the line command >> rank(A)

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